



**SRI MANAKULA VINAYAGAR**  
**ENGINEERING COLLEGE**  
(An Autonomous Institution)

Puducherry

**DEPARTMENT OF ELECTRICAL AND ELECTRONICS  
ENGINEERING**

**B.TECH. HONOURS / MINOR PROGRAMME**  
**ELECTRIC VEHICLES**

**ACADEMIC REGULATIONS 2023  
(R-2023)**

**CURRICULUM AND SYLLABI**



## B. Tech Honours / Minor Programme - ELECTRIC VEHICLES

### CURRICULUM

COURSE DETAILS												
Sl. No.	Semester	Course Code	Course Title	Course Type**	Category	Periods			Credits	Max. Marks		
						L	T	P		CAM	ESM	Total
1	IV	U23VXT401	Electrical Vehicles: Design, Dynamics and Testing	T	PC / IC	3	-	-	3	25	75	100
2	V	U23VXT502	Energy Storage and Battery Management System	T	PC / IC	3	-	-	3	25	75	100
3	VI	U23VXB603	Electric Drives and Controls	B	PC / IC	3	-	2	4	50	50	100
4	VII	U23VXB704	Modelling and Simulation of EHV	B	PC / IC	3	-	2	4	50	50	100
5	VIII	U23VXT805	Autonomous and Connected Vehicles	T	PC / IC	3	-	-	3	25	75	100
6	VIII	U23VXW806	Project Work	PA	PC / IC	-	-	4	2	50	50	100
<b>Total</b>									<b>19</b>	<b>225</b>	<b>375</b>	<b>600</b>
<b>Equivalent NPTEL courses##</b>												
1	IV	U23VXT401	Electrical Vehicles: Design, Dynamics and Testing	Vehicle Dynamics and Electric Motor Drives					3	<b>12 WEEKS COURSE</b>		
2	IV			Vehicles and Renewable Energy					3			
3	V	U23VXT502	Energy Storage and Battery Management System	Electrochemical Energy Storage					3			

## The student shall be given an option to earn 3 credits through one 12-week NPTEL course (Equivalent) instead of any one theory course listed for Honour / Minor degree programme and shall be completed before the commencement of eighth semester. The equivalent courses are subject to change based on its availability as per NPTEL course list.

\*\* T – Theory, B – Theory cum Practical, PA – Project Work

Department	EEE			Programme: <b>B.Tech Honours / Minor – Electric Vehicles</b>						
Semester	IV			Course Category Code: <b>PC/ IC</b>		End Semester Exam Type: <b>TE*</b>				
Course Code	<b>U23VXT401</b>			Periods/Week		Credit	Maximum Marks			
				L	T	P	C	CAM	ESE	TM
Course Name	<b>ELECTRICAL VEHICLES: DESIGN, DYNAMICS AND TESTING</b>			<b>3</b>	<b>-</b>	<b>-</b>	<b>3</b>	<b>25</b>	<b>75</b>	<b>100</b>
Common to ALL Branches										
Prerequisite	Engineering Mechanics									
Course Outcomes	<b>On completion of the course, the students will be able to</b>								BT Mapping (Highest Level)	
	<b>CO1</b>	Summarize the basic functions of both Electric and Hybrid vehicles and their performance.							<b>K2</b>	
	<b>CO2</b>	Illustrate the automobile configurations, packaging, structural systems, aerodynamics and power demand, etc.,							<b>K3</b>	
	<b>CO3</b>	Predict the vehicle resistance and proficiently optimize the powertrain performance for FWD, RWD, and multi-wheel drive systems.							<b>K3</b>	
	<b>CO4</b>	Examine the vehicle testing, homologation, and standards compliance for safe automotive engineering.							<b>K3</b>	
	<b>CO5</b>	Demonstrate the requirement of vehicular safety systems and road regulations							<b>K3</b>	
<b>UNIT- I</b>	<b>Introduction</b>						<b>Periods: 9</b>			
History - Components of Electric Vehicle (EV)- General Layout of EV- EV classification- Comparison with Internal combustion Engine- Technology- Advantages and Disadvantages of EV. Hybrid vehicle – advantages- disadvantages- Architecture and energy flow– series, parallel, series-parallel- Drive train for hybrid and electric vehicles-Hybrid vehicle operating modes.										<b>CO1</b>
<b>UNIT- II</b>	<b>Vehicle Dynamics</b>						<b>Periods: 9</b>			
General Configuration of Automobile- Body and Chassis Fundamentals- General Packaging- Types of Structural System- Backbone Construction- Body and Chassis Materials. Automotive Aero-dynamics- Vehicle Power Demand Analysis- Types of suspension and drive- Tyre Mechanics-Tyres and wheels- Tyre characteristics- Vehicle handling and stability- Automotive instrumentation										<b>CO2</b>
<b>UNIT- III</b>	<b>Vehicle Design</b>						<b>Periods: 9</b>			
Vehicle resistance- <b>Types:</b> Rolling Resistance- grading resistance. Aerodynamic drag-vehicle performance- Calculation of Acceleration Force- maximum speed- Total Tractive Effort-Torque Required on drive Wheel- Transmission- Differential- clutch and gearbox- Braking performance. Front-Wheel Drive (FWD) Powertrains- Rear-Wheel Drive Powertrains (RWD)- Multi-Wheel Drive Powertrains (AWD and 4WD)										<b>CO3</b>
<b>UNIT- IV</b>	<b>Vehicle Testing and Homologation</b>						<b>Periods: 9</b>			
Need of vehicle testing and homologation- testing organizations- testing standards (AIS)- Hierarchy of testing- Individual component approval/testing- System level approval and Whole vehicle approval/testing- Conformity of production tests- Crash test- side impact test- rollover test- Impact test- Track testing										<b>CO4</b>
<b>UNIT- V</b>	<b>Vehicular Safety and Government norms</b>						<b>Periods: 9</b>			
Road and Automotive Safety Systems- Active and passive safety- Safety Regulations for vehicular application- occupant protection- Traffic signs- traffic rules- Government Norms- Regulations and Policies- penalties and procedures.										<b>CO5</b>
<b>Lecture Periods:45</b>			<b>Tutorial Periods:-</b>		<b>Practical Periods:-</b>			<b>Total Periods: 45</b>		
<b>Text Books:</b>										
1. Mehrdad Ehsani, Yimin Gao, Stefano Longo, Kambiz Ebrahimi, “Modern Electric, Hybrid Electric, and Fuel Cell Vehicles”, CRC Press, 2018. 2. David C Barton, John D Fieldhouse, “Automotive Chassis Engineering”, Springer International Publishing, 2018.										
<b>Reference Books:</b>										
1. Thomas Gillespie, “Fundamentals of Vehicle Dynamics”, SAE International, April 2021. 2. Ulrich Seiffert, Lothar, Wech, “Automotive Safety Handbook, SAE International, 2007.										
<b>Web Reference:</b>										
1. <a href="https://www.nhtsa.gov/">https://www.nhtsa.gov/</a> 2. <a href="https://www.ais.gov.in/">https://www.ais.gov.in/</a> 3. <a href="https://www.opal-rt.com/automotive-overview/">https://www.opal-rt.com/automotive-overview/</a>										

\* TE – Theory Exam, LE – Lab Exam

## COs/POs/PSOs Mapping

COs	Program Outcomes (POs)												Program Specific Outcomes (PSOs)		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
1	3	2	3	2	1	2	1	-	-	-	-	1	3	3	2
2	3	2	3	2	1	2	1	-	-	-	-	1	3	3	2
3	3	2	3	2	1	2	1	-	-	-	-	1	3	3	2
4	3	2	3	2	1	2	1	-	-	-	-	1	3	3	2
5	3	2	3	2	1	2	1	-	-	-	-	1	3	3	2

Correlation Level: 1 – Low, 2 – Medium, 3 – High

## Evaluation Methods

	Continuous Assessment Marks (CAM)					End Semester Examination##	Total Marks (CAM+ESM)
	CAT 1	CAT 2	Model##	Assignment#	Attendance##		
Portion for Test	2 Units	2 Units	All 5 Units			All 5 Units	
Assessment Methodology	MCQ Test	MCQ Test	Written Exam	Individual Task #		Written Exam	
	50 Questions for Analytical Course 75 Questions for Theory Course						
Duration of the Test	1 hour 30 Minutes	1 hour 30 Minutes	3 hours		3 hours		
Test Marks	50	50	75	20	5	75	
Weightage for CAM	5	5	5	5	5		
CAM / ESE Marks	CAM Marks = 25					ESE Marks = 75	100

# Open Book Analytical Exam/Analyse Real world problems and propose solutions/ Tool or Subject Proficiency Analysis – Test the Students skill by giving individual task/ Paper Presentation/Micro Project Presentation/Idea Presentation for the Societal Problem;(Questions standard shall be of level 3 or more in Blooms Taxonomy)

## Distribution of Marks for Attendance, the Question Paper Pattern for Model and ESE are same as given in B. Tech. Regulations R2023 for Theory Courses.

**B.Tech. Honours / Minor – Electric Vehicles**

Dr. P. Jamuna

**Text Books**

1. Alfred Rufer, "Energy Storage Systems and Components", CRC Press, 2018.
2. Ibrahim Dincer, Halil S. Hamut and Nader Javani, "Thermal Management of Electric Vehicle Battery Systems", John Wiley & Sons Ltd., 2016.

**Reference Books**

1. James Larminie, John Lowry, "Electric Vehicle Technology Explained", John Wiley & Sons Ltd, 2012.
2. NITI Aayog, Handbook of Electric Vehicle Charging Infrastructure Implementation, Version 1, 2021.
3. T R Crompton, "Battery", Newnes- Reed Educational and Professional Publishing Ltd. 3<sup>rd</sup> Edition, 2000.
4. F. Beguin and E. Frackowiak, "Super capacitors- materials, Systems and Applications", Wiley-VCH & Company, 2013.
5. V.Hacker, S. Mitsushima, "Fuel Cells and Hydrogens: From Fundamentals to applied Research", Elsevier, 2018.
6. Fraunhofer IEE, IIT Bombay, DTU, and IIT Comillas, A Critical Review: Smart Charging Strategies and Technologies for Electric Vehicles, NDC-TIA, Nov. 2021.
7. D. Kettles, Electric Vehicle Charging Technology Analysis and Standards, Florida Solar Energy Center, Feb. 2015

**Web References**

1. <https://archive.nptel.ac.in/courses/108/103/108103009/>
2. <https://www.nhtsa.gov/>
3. <https://www.ais.gov.in/>
4. <https://www.opal-rt.com/automotive-overview/>
5. [https://apem-journal.org/Archives/2019/APEM14-1\\_065-079.pdf](https://apem-journal.org/Archives/2019/APEM14-1_065-079.pdf)
6. <https://ouci.dntb.gov.ua/works/4rrWg5X4/>
7. <https://www.beny.com/challenges-and-solutions-in-electric-vehicle-charging-infrastructure-development/>

\* TE – Theory Exam, LE – Lab Exam

**COs/POs/PSOs Mapping**

COs	Program Outcomes (POs)												Program Specific Outcomes (PSOs)		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
1	3	2	3	2	-	2	1	-	-	-	-	1	3	3	2
2	3	2	3	2	-	2	1	-	-	-	-	1	3	3	2
3	3	2	3	2	-	2	1	-	-	-	-	1	3	3	2
4	3	2	3	2	-	2	1	-	-	-	-	1	3	3	2
5	3	2	3	2	-	2	1	-	-	-	-	1	3	3	2

Correlation Level: 1 – Low, 2 – Medium, 3 – High

**Evaluation Methods**

	Continuous Assessment Marks (CAM)					End Semester Examination <sup>##</sup>	Total Marks (CAM+ESM)
	CAT 1	CAT 2	Model <sup>##</sup>	Assignment <sup>#</sup>	Attendance <sup>##</sup>		
Portion for Test	2 Units	2 Units	All 5 Units			All 5 Units	
Assessment Methodology	MCQ Test	MCQ Test	Written Exam	Individual Task #		Written Exam	
	50 Questions for Analytical Course 75 Questions for Theory Course						
Duration of the Test	1 hour 30 Minutes	1 hour 30 Minutes	3 hours			3 hours	
Test Marks	50	50	75	20		5	
Weightage for CAM	5	5	5	5	5		
CAM / ESE Marks	CAM Marks = 25					ESE Marks = 75	100

# Open Book Analytical Exam/Analyse Real world problems and propose solutions/ Tool or Subject Proficiency Analysis – Test the Students skill by giving individual task/ Paper Presentation/Micro Project Presentation/Idea Presentation for the Societal Problem;(Questions standard shall be of level 3 or more in Blooms Taxonomy)

## Distribution of Marks for Attendance, the Question Paper Pattern for Model and ESE are same as given in B. Tech. Regulations R2023 for Theory Courses.



Department	EEE		Programme: <b>B.Tech Honours/ Minor – Electric Vehicles</b>						
Semester	VI		Course Category: <b>PC/IC</b>			End Semester Exam Type: <b>TE*</b>			
Course Code	<b>U23VXB603</b>		Periods/Week			Credit	Maximum Marks		
			L	T	P	C	CAM	ESE	TM
Course Name	<b>ELECTRIC DRIVES AND CONTROLS</b>		<b>3</b>	<b>0</b>	<b>2</b>	<b>4</b>	<b>50</b>	<b>50</b>	<b>100</b>
Common to ALL Branches									
Prerequisite	Electrical Machines								
Course Outcomes	<b>On completion of the course, the students will be able to</b>								BT Mapping (Highest Level)
	<b>CO1</b>	Comprehend the types, design, and sizing of electric vehicle motors, including their torque-speed characteristics and role in EV propulsion systems.							<b>K2</b>
	<b>CO2</b>	Analyze the operation and performance of DC and AC motor drives with speed control techniques.							<b>K2</b>
	<b>CO3</b>	Apply the various control techniques for PMSM and BLDC motor drives for the performance optimization.							<b>K3</b>
	<b>CO4</b>	Analyze and implement DC and AC motor control techniques for various Electric Vehicles.							<b>K4</b>
	<b>CO5</b>	Implement control techniques for PMSM, and BLDC motor drives, optimizing performance and minimizing torque ripple.							<b>K4</b>
<b>UNIT – I</b>	<b>Introduction to EV Drives</b>					<b>Periods:10</b>			
<b>Overview of EV Motors:</b> Types of motors used in electric vehicles (EVs) and their classifications. <b>Traction Motors Design:</b> Design principles and sizing considerations for EV traction motors. <b>Torque-Speed Characteristics:</b> Analysis of constant-torque and constant-power modes in motor performance. Selection of Motor Power and converter Rating. <b>Motor Comparison for EVs:</b> Suitability analysis of motors for 2W, 3W, 4-wheelers, and large vehicles.									<b>CO1</b>
<b>UNIT – II</b>	<b>DC Drives and Induction Motor Drives</b>					<b>Periods:10</b>			
<b>DC Drives:</b> Phase controlled DC-Drives: Operation with continuous and discontinuous modes; Chopper Controlled DC Drives, Multi-Quadrant Operation, harmonics control in chopper, speed control method, closed loop control scheme. <b>Induction Motor Drives:</b> Speed control techniques: Stator voltage control, Variable frequency control, V/f control, Static rotor resistance control and Slip power recovery control schemes, Slip compensation technique. Field-oriented control and direct torque control of induction motors for EVs.									<b>CO2</b>
<b>UNIT – III</b>	<b>BLDC and PMSM Drives</b>					<b>Periods:10</b>			
<b>BLDC Motor Drives:</b> Principles of BLDC motor operation, inverter switching schemes for AC and DC, trapezoidal back EMF control, and design criteria for BLDC drives in EVs. <b>PMSM Drives:</b> Permanent Magnet Synchronous Motor (PMSM) construction, braking methods, field-oriented and flux-weakening control, and sensorless operation.									<b>CO3</b>
<b>UNIT – IV</b>	<b>Electric Drives Practice -I</b>					<b>Periods:15</b>			
1. Demonstration of wiring layout of electric vehicle. 2. Speed control of DC drives using phase-controlled rectifier 3. Speed control of DC drives using chopper control. 4. Performance Analysis of Induction motor Drive. 5. V/f Control of PWM Inverter Based Three Phase Induction Motor 6. Simulation of Rotor Resistance Scheme in Wound-Rotor Induction Motor									<b>CO4</b>
<b>UNIT – V</b>	<b>Electric Drives Practice -II</b>					<b>Periods:15</b>			
1. Speed control of FPGA based BLDC motor Drive 2. Simulation of PMSM speed control using the Field-Oriented Control method. 3. Sensorless Field Oriented Control for Permanent Magnet Synchronous Motor drive 4. Torques ripples reduction techniques in BLDC and PMSM motor drives. 5. Regenerative/ Dynamic breaking operation for AC motor using simulation software 6. Study of SRM motor drive fed by PWM inverter using simulation software.									<b>CO5</b>
<b>Lecture Periods: 30</b>		<b>Tutorial Periods: -</b>		<b>Practical Periods: 30</b>			<b>Total Periods: 60</b>		
<b>Text Books</b>									
3. KT. Chau, "Electric Vehicle Machines and Drives: Design, Analysis, and Application," Wiley-IEEE Press, 1st Edition, 2015. 4. John G. Hayes, G. Abas Goodarzi, "Electric Powertrain: Energy Systems, Power Electronics and Drives for Hybrid, Electric and Fuel Cell Vehicles," Wiley-Blackwell, 1st Edition, 2018.									

### Reference Books

1. C.G. Hochgraf, M.J. Ryan, and H.L. Wiegman, "Engine Control Strategy for a Series Hybrid Electric Vehicle," Warrendale, PA, 2nd Edition, 2002.
2. Seth Leitman, Bob Brant, "Build Your Own Electric Vehicle," McGraw-Hill, 3rd Edition, 2013.
3. C.C. Chan, K.T. Chau, "Modern Electric Vehicle Technology," Oxford University Press, 1st Edition, 2001.

### Web References

8. <https://archive.nptel.ac.in/courses/108/104/108104140/>
9. [https://onlinecourses.nptel.ac.in/noc24\\_ee30/preview](https://onlinecourses.nptel.ac.in/noc24_ee30/preview)
10. <https://www.slideshare.net/slideshow/electric-drives-and-controls-unit-1-introduction/250009052>
11. <https://www.mygreatlearning.com/academy/learn-for-free/courses/introduction-to-inverters-and-electric-drive>
12. [https://onlinecourses.swayam2.ac.in/ntr24\\_ed16/preview](https://onlinecourses.swayam2.ac.in/ntr24_ed16/preview)

\* TE – Theory Exam, LE – Lab Exam

### COs/POs/PSOs Mapping

COs	Program Outcomes (POs)												Program Specific Outcomes (PSOs)		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
1	3	2	3	2	-	2	1	-	2	-	-	2	3	3	3
2	3	2	3	2	-	2	1	-	2	-	-	2	3	3	3
3	3	2	3	2	-	2	1	-	2	-	-	2	3	2	3
4	3	2	3	2	-	2	1	-	2	-	-	2	3	2	3
5	3	2	3	2	-	2	1	-	2	-	-	2	3	2	3

Correlation Level: 1 – Low, 2 – Medium, 3 – High

### Evaluation Methods

Assessment	Continuous Assessment Marks (CAM) – Maximum 50 Marks										#End Semester Examination (ESE) (Theory)	Total Marks (CAM+ESE)
	Continuous Assessment (Theory)					Continuous Assessment (Practical)						
	CAT 1	CAT 2	Model <sup>###</sup>	Attendance <sup>###</sup>	Total	Conduction of Practical	Report	Viva	Total	End Semester Examination (ESE) Marks (Practical)		
Portion for Test	1 ½ Units	1 ½ Units	All 3 Units								All 3 Units	
Assessment Methodology	MCQ Test	MCQ Test	Written Exam							Practical Exam	Written Exam	
	50 Questions for Analytical Course 75 Questions for Theory Course											
Duration of the Test	1 hour 30 Minutes	1 hour 30 Minutes	3 hours							3 hours	3 hours	
Marks	50	50	75	5		15	10	5	30*	30	75 (To be weighted for 50 Marks)	
Weightage of CAM	2.5	2.5	2.5	2.5	10	*To be weighted for 10 Marks			10	30		
CAM / ESE Marks	CAM Marks =10+10+30=50										ESE Marks = 50	100

## Distribution of Marks for Attendance, the Question Paper Pattern for Model and ESE are same as given in B.Tech. Regulations R2023 for Theory cum practical Courses



Department	EEE				Programme: <b>B.Tech Honour / Minor – Electric Vehicles</b>						
Semester	VII				Course Category Code: <b>PC/ IC</b>		End Semester Exam Type: <b>TE*</b>				
Course Code	<b>U23VXB704</b>				Periods / Week		Credit	Maximum Marks			
					L	T	P	C	CAM	ESE	TM
Course Name	<b>MODELLING AND SIMULATION OF EHV</b>				<b>3</b>	<b>-</b>	<b>2</b>	<b>4</b>	<b>50</b>	<b>50</b>	<b>100</b>
Common to All Branches											
Prerequisite	Electrical Machines										
Course Outcomes	<b>On completion of the course, the students will be able to</b>										BT Mapping (Highest Level)
	<b>CO1</b>	Apply the concept of modeling for electric vehicle and predict the performance.									<b>K3</b>
	<b>CO2</b>	Describe the drive train characteristics of electric vehicles									<b>K3</b>
	<b>CO3</b>	Analysis the vehicle dynamic control and energy management techniques									<b>K3</b>
	<b>CO4</b>	Design and simulate the Electric Vehicle Power train for the analysis									<b>K4</b>
	<b>CO5</b>	Implement the battery management system for the battery pack									<b>K4</b>
<b>UNIT - I</b>	<b>Modeling of Electric Vehicles</b>							<b>Periods: 10</b>			
Modeling Vehicle Acceleration - Acceleration performance parameters, modeling of acceleration of an electric scooter, modeling of acceleration of a small car. Electric Vehicle Modeling - Tractive Effort- Rolling resistance force- Aerodynamic drag- Hill climbing force- Acceleration force- Total tractive effort - Modeling Electric Vehicle Range - Driving cycles - Constant velocity range modeling - Range modeling of battery electric vehicles - fuel cell vehicles - hybrid electric vehicles										<b>CO1</b>	
<b>UNIT - II</b>	<b>EV Drive Train Characteristics</b>							<b>Periods: 10</b>			
Modeling and Characteristics of EV/HEV Power trains Components - ICE Performance Characteristics, Electric Motor Performance Characteristics - Battery Performance Characteristics - Transmission and Drive train Characteristics - Regenerative Braking Characteristics - Driving Cycles - Modeling and Analysis of Electric and Hybrid Electric Vehicles Propulsion and Braking - Longitudinal Dynamics Equation of Motion - Vehicle Propulsion Modeling and Analysis - Vehicle Braking Modeling and Analysis.										<b>CO2</b>	
<b>UNIT - III</b>	<b>Vehicle Dynamic Control and Energy Management</b>							<b>Periods: 10</b>			
Control of Electric and Hybrid Electric Vehicle Dynamics - Fundamentals of Vehicle Dynamic Control (VDC) Systems, VDC Implementation on Electric and Hybrid Vehicles – Case Studies, Rechargeable Battery Vehicles, Hybrid Vehicles, Fuel Cell Powered Vehicles. Handling Analysis of Electric and Hybrid Electric Vehicles - Simplified Handling Models Energy/Power Allocation and Management - Power/Energy Management Controllers – Rule Based Control Strategies – Optimization - Based Control Strategies.										<b>CO3</b>	
<b>UNIT - IV</b>	<b>Modeling of EHV Practice -I</b>							<b>Periods: 15</b>			
1. Determination of SoC, DoD, Cell Cycle for battery 2. Mathematical Modeling of lithium ion cell and design of battery pack / format. 3. Design and Development of Battery Pack for specified Rating 4. Electric Vehicle Power train Simulation using MATLAB/Simulink 5. Transmission and Drive train Simulation for EVs in MATLAB/Simulink 6. Rule-Based Power Management for Hybrid Electric Vehicles in Simulink										<b>CO4</b>	
<b>UNIT - V</b>	<b>Modeling of EHV Practice -II</b>							<b>Periods: 15</b>			
1. Implementation of Wiring Diagram for a 36V, 10S Battery Management System (BMS) 2. Implementation of Wiring Diagram and Testing of Smart BMS for a 48V, 15S battery pack 3. Battery Management System using battery pack equalizer through active balancer with Bluetooth monitoring 4. Microcontroller- Programmable Battery Management System 5. Design and Implementation of Conductive Charging Setup 6. Simulation of Vehicle Dynamic Control for Hybrid and Battery Electric Vehicles										<b>CO5</b>	
<b>Lecture Periods: 30</b>			<b>Tutorial Periods:-</b>			<b>Practical Periods: 30</b>			<b>Total Periods: 60</b>		
<b>Text Books</b>											
1. James Larminie, John Lowry, “Electric Vehicle Technology Explained”, John Wiley & Sons Ltd., 2 <sup>nd</sup> Edition, 2012. 2. Amir Khajepour, Saber Fallah and AvestaGoodarzi, “Electric and Hybrid Vehicles -Technologies, Modelling and Control: A Mechatronic Approach”, John Wiley & Sons Ltd, 1 <sup>st</sup> Edition, 2014.											
<b>Reference Books</b>											

1. Antoni Szumanowski, "Hybrid Electric Power Train Engineering and Technology: Modelling, Control, and Simulation", Idea Group, 1<sup>st</sup> Edition, 2013.
2. Mehrdad Ehsani, Yimin Gao, Ali Emadi, "Modern Electric, Hybrid Electric, and Fuel Cell Vehicles - Fundamentals, Theory, and Design, CRC Press, 2<sup>nd</sup> Edition", 2017.

### Web References

1. [https://archive.nptel.ac.in/content/syllabus\\_pdf/108103009.pdf](https://archive.nptel.ac.in/content/syllabus_pdf/108103009.pdf)
2. [https://www.researchgate.net/publication/309548969\\_MODELING\\_AND\\_SIMULATION\\_OF\\_HYBRID\\_ELECTRIC\\_VEHICLES](https://www.researchgate.net/publication/309548969_MODELING_AND_SIMULATION_OF_HYBRID_ELECTRIC_VEHICLES)
3. <https://www.sciencedirect.com/science/article/pii/S2405896322014446>
4. [https://www.academia.edu/1003352/A\\_Matlab\\_Based\\_Modeling\\_and\\_Simulation\\_Package\\_for\\_Electric\\_and\\_Hybrid\\_Electric\\_Vehicle\\_Design](https://www.academia.edu/1003352/A_Matlab_Based_Modeling_and_Simulation_Package_for_Electric_and_Hybrid_Electric_Vehicle_Design)
5. [https://www.academia.edu/90442341/Modeling\\_and\\_Simulation\\_of\\_Hybrid\\_Electric\\_Vehicle\\_Power\\_Systems?uc-sb-sw=17290990](https://www.academia.edu/90442341/Modeling_and_Simulation_of_Hybrid_Electric_Vehicle_Power_Systems?uc-sb-sw=17290990)

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### COs/POs/PSOs Mapping

COs	Program Outcomes (POs)												Program Specific Outcomes (PSOs)		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
1	3	3	3	3	3	2	2	-	2	2	-	2	3	3	3
2	3	3	3	3	3	2	2	-	2	2	-	2	3	3	3
3	3	3	3	3	3	2	2	-	2	2	-	2	3	3	3
4	3	3	3	3	3	2	2	-	2	2	-	2	3	3	3
5	3	3	3	3	3	2	2	-	2	2	-	2	3	3	3

Correlation Level: 1 - Low, 2 - Medium, 3 – High

### Evaluation Methods

Assessment	Continuous Assessment Marks (CAM) – Maximum 50 Marks										##End Semester Examination (ESE) (Theory)	Total Marks (CAM+ESE)
	Continuous Assessment (Theory)					Continuous Assessment (Practical)						
	CAT 1	CAT 2	Model##	Attendance##	Total	Conduction of Practical	Report	Viva	Total	End Semester Examination (ESE) Marks (Practical)		
Portion for Test	1 ½ Units	1 ½ Units	All 3 Units								All 3 Units	
Assessment Methodology	MCQ Test	MCQ Test	Written Exam							Practical Exam	Written Exam	
	50 Questions for Analytical Course 75 Questions for Theory Course											
Duration of the Test	1 hour 30 Minutes	1 hour 30 Minutes	3 hours							3 hours	3 hours	
Marks	50	50	75	5		15	10	5	30*	30	75 (To be weighted for 50 Marks)	
Weightage of CAM	2.5	2.5	2.5	2.5	10	*To be weighted for 10 Marks			10	30		
CAM / ESE Marks	CAM Marks =10+10+30=50										ESE Marks = 50	100

## Distribution of Marks for Attendance, the Question Paper Pattern for Model and ESE are same as given in B.Tech. Regulations R2023 for Theory cum practical Courses

Department	EEE		Programme: <b>B.Tech Honours / Minor – Electric Vehicles</b>							
Semester	VIII		Course Category: <b>PC/ IC</b>			End Semester Exam Type : <b>TE*</b>				
Course Code	<b>U23VXT805</b>		Periods/Week			Credit	Maximum Marks			
			L	T	P	C	CAM	ESE	TM	
Course Name	<b>AUTONOMOUS AND CONNECTED VEHICLES</b>		<b>3</b>	<b>-</b>	<b>-</b>	<b>3</b>	<b>25</b>	<b>75</b>	<b>100</b>	
Common to All Branches										
Prerequisite	Electrical Vehicles: Design, Dynamics and Testing									
Course Outcomes	<b>On completion of the course, the students will be able to</b>							BT Mapping (Highest Level)		
	<b>CO1</b>	Summarize the advanced driver assistance systems for connected vehicle							<b>K2</b>	
	<b>CO2</b>	Interpret the recent global navigation and Lidar technology for vehicle integration							<b>K2</b>	
	<b>CO3</b>	Apply the Perception path, Deep Learning, planning for autonomous and connected vehicles							<b>K3</b>	
	<b>CO4</b>	Demonstrate the hardware used in E-vehicle an computer architecture for Autonomous Driving							<b>K3</b>	
	<b>CO5</b>	Illustrate the ECU evolution in architecture by software defined vehicles							<b>K3</b>	
<b>UNIT – I</b>	<b>Autonomous System Architecture</b>					<b>Periods: 9</b>				
Overview-Autonomous Driving Algorithms-Sensing- Perception- Object Recognition and Tracking- Action- Autonomous Driving Client System-Robot Operating System- Hardware Platform- Autonomous Driving Cloud Platform-HD Map Production, Deep Learning Model Training.									<b>CO1</b>	
<b>UNIT – II</b>	<b>Autonomous Vehicle Integration</b>					<b>Periods: 9</b>				
Localization with GNSS- GNSS Overview- GNSS Error Analysis- Satellite-based Augmentation Systems- Real-Time Kinematic and Differential GPS- Precise Point Positioning- GNSS INS Integration. Localization with LiDAR and High-Definition Maps- LiDAR Overview-High-Definition Maps Overview- Localization with LiDAR and HD Map- Visual Odometry- Stereo Visual Odometry- Monocular Visual Odometry- Visual Inertial Odometry- Dead Reckoning and Wheel Odometry- Wheel Encoders- Wheel Odometry Errors- Reduction of Wheel Odometry Errors									<b>CO2</b>	
<b>UNIT – III</b>	<b>Perception and Deep Learning in Autonomous Driving Perception</b>					<b>Periods: 9</b>				
Introduction- Datasets- Detection- Segmentation- Stereo- Optical Flow- Scene Flow- Tracking- Deep Learning in Autonomous Driving- Convolutional Neural Networks- Detection- Semantic Segmentation- Stereo and Optical Flow- Planning and Control Overview- Architecture-Traffic Prediction -Lane Level Routing									<b>CO3</b>	
<b>UNIT – IV</b>	<b>Client Systems for Autonomous Driving</b>					<b>Periods: 9</b>				
Hardware platform for autonomous driving- Operating system-ROS overview- system reliability- performance improvement- Resource Management And Security- Computing Platform- existing computing solution- computer architecture design exploration- Autonomous Driving on Mobile Processor- V2V-System Architecture-Safet application- V2I overview- BIM- V2P- System Architecture- Vehicle Warning Strategy									<b>CO4</b>	
<b>UNIT – V</b>	<b>Cloud Platform for Autonomous Driving</b>					<b>Periods: 9</b>				
Infrastructure-distributed computing framework-distributed storage-heterogeneous computing- Simulation-BINPIPERDD-connecting spark and ROS-performance- Model training-need of SPARK-Training platform architecture-HD map generation. Autonomous driving-Vehicle Onboard Architecture- ECU software architecture –AUTOSAR- COVESA									<b>CO5</b>	
<b>Lecture Periods: 45</b>		<b>Tutorial Periods:-</b>		<b>Practical Periods: -</b>			<b>Total Periods: 45</b>			
<b>Text Books</b>										
1. Shaoshan Liu, Liyun Li, Jie Tang, Shuang Wu, Jean-Luc Gaudiot, “Creating Autonomous Vehicle Systems”, Morgan & Claypool Publishers, 1 <sup>st</sup> Edition, 2018 2. Radovan Miucic, “Connected Vehicles: Intelligent Transportation Systems”, Springer, 2018										
<b>Reference Books</b>										
1. Domokos Esztergár-Kiss, Pierluigi Coppola, “Autonomous Vehicles and Future Mobility”, Elsevier, 2019. 2. Mehrdad Ehsani, Yimin Gao, Ali Emadi, “Modern Electric, Hybrid Electric, and Fuel Cell Vehicles Fundamentals, Theory and Design”, CRC Press, 2 <sup>nd</sup> Edition, 2017.										

### Web References

1. <https://www.ibm.com/blogs/digitale-perspektive/2023/06/the-software-defined-vehicle/>
2. <https://www.sciencedirect.com/science/article/pii/S2405896322014446>
3. <https://www.ais.gov.in/>
4. <https://www.opal-rt.com/automotive-overview/>

\* TE – Theory Exam, LE – Lab Exam

### COs/POs/PSOs Mapping

COs	Program Outcomes (POs)												Program Specific Outcomes (PSOs)		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
1	3	3	3	2	3	-	-	-	-	-	-	2	3	3	3
2	3	3	3	2	3	-	-	-	-	-	-	2	3	3	3
3	3	3	3	2	3	-	-	-	-	-	-	2	3	3	3
4	3	3	3	2	3	-	-	-	-	-	-	2	3	3	3
5	3	3	3	2	3	-	-	-	-	-	-	2	3	3	3

Correlation Level: 1 - Low, 2 - Medium, 3 – High

### Evaluation Methods

	Continuous Assessment Marks (CAM)					End Semester Examination##	Total Marks (CAM+ESM)
	CAT 1	CAT 2	Model##	Assignment#	Attendance##		
Portion for Test	2 Units	2 Units	All 5 Units			All 5 Units	
Assessment Methodology	MCQ Test	MCQ Test	Written Exam	Individual Task #		Written Exam	
	50 Questions for Analytical Course 75 Questions for Theory Course						
Duration of the Test	1 hour 30 Minutes	1 hour 30 Minutes	3 hours			3 hours	
Test Marks	50	50	75	20		5	
Weightage for CAM	5	5	5	5	5		
CAM / ESE Marks	CAM Marks = 25					ESE Marks = 75	100

# Open Book Analytical Exam/Analyse Real world problems and propose solutions/ Tool or Subject Proficiency Analysis – Test the Students skill by giving individual task/ Paper Presentation/Micro Project Presentation/Idea Presentation for the Societal Problem;(Questions standard shall be of level 3 or more in Blooms Taxonomy)

## Distribution of Marks for Attendance, the Question Paper Pattern for Model and ESE are same as given in B. Tech. Regulations R2023 for Theory Courses.

Department	EEE	Programme: <b>B.Tech Honours / Minor – Electric Vehicles</b>						
Semester	VIII	Course Category: <b>PC/ IC</b>		End Semester Exam Type : <b>LE*</b>				
Course Code	<b>U23VXW806</b>	Periods/Week			Credit	Maximum Marks		
		L	T	P	C	CAM	ESE	TM
Course Name	<b>Project Work</b>	-	-	<b>4</b>	<b>2</b>	<b>50</b>	<b>50</b>	<b>100</b>

Common to All Branches

Prerequisite	-							
Course Outcomes	<b>On completion of the course, the students will be able to</b>							BT Mapping (Highest Level)
	<b>CO1</b>	Apply literature survey techniques to identify and define the problem statement for the project						<b>K3</b>
	<b>CO2</b>	Comprehend, plan, and implement a project related to electric mobility						<b>K2</b>
	<b>CO3</b>	Develop a real-time application utilizing electric vehicle components, processes, or systems						<b>K3</b>
	<b>CO4</b>	Interpret and apply knowledge of publication and copyright processes in research						<b>K3</b>
	<b>CO5</b>	Justify and present project findings through structured oral and written reports						<b>K4</b>

**Course Description**

Student must select a project topic either from published lists or propose a suitable topic in consultation with his/her supervisor. The objective of the project is to enhance understanding of fundamental principles by applying them to a new challenge, which may involve designing and manufacturing a device, conducting research, developing a computer or management project, or solving a design problem.

The project progress will be assessed through a minimum of two reviews. The project evaluation shall be carried out by a Project evaluation committee comprising the Head of the Department or his/her nominee (Chairperson), Project coordinator (Professor / Associate Professor) and the project supervisor(s). The End Semester Examination for the project work will include an evaluation of the final project report by an external examiner, followed by a viva-voce examination conducted by a panel comprising the external examiner and an internal examiner.

<b>Lecture Periods: -</b>	<b>Tutorial Periods:-</b>	<b>Practical Periods: 60</b>	<b>Total Periods: 60</b>
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\* TE – Theory Exam, LE – Lab Exam

**COs/POs/PSOs Mapping**

COs	Program Outcomes (POs)												Program Specific Outcomes (PSOs)		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
<b>1</b>	3	3	3	2	3	-	-	-	3	3	-	2	3	3	3
<b>2</b>	3	3	3	2	3	2	2	2	3	3	2	2	3	3	3
<b>3</b>	3	3	3	2	3	2	-	-	3	3	2	2	3	3	3
<b>4</b>	3	3	3	2	3	-	2	-	3	3	-	2	3	3	3
<b>5</b>	3	3	3	2	3	-	2	2	3	3	-	2	3	3	3

Correlation Level: 1 - Low, 2 - Medium, 3 – High

**Evaluation Methods**

Sl. No	Description			Weightage
<b>1</b>	<b>Continuous Assessment Marks</b>			
a	Review 1	Review Committee	15	25
		Supervisor	10	
b	Review 2	Review Committee	15	25
		Supervisor	10	
	<b>Total CAM</b>			<b>50</b>
<b>2</b>	<b>End Semester Marks</b>			
a	Evaluation of project work report and Viva-voce	Report	15	50
		Presentation and Viva	20	
		Demonstration	15	
	<b>Total ESM</b>			<b>50</b>
	<b>Total Marks</b>			<b>100</b>